Outline

- •Organization overview
- •Instruction Set Architecture (ISA)
- •Instruction set design principles
- •ISA classes

A Look Ahead

Chapter 3

- •Overview of computer organization
 - ≻Fetch/Execute cycle
 - ➤Computer operations
 - ➤addressing modes
- •Instruction set design principles
- •Overview of MIPS architecture
- •Stored program concept
- •Learn a subset of MIPS assembly language
- •Show how MIPS instructions are represented in machine language
- •Contrast MIPS architecture with other X86 and PowerPC architectures

Organization Review

- All computers consist of five components
 - Processor: (1) datapath and (2) control
 - -(3) Memory
 - (4) Input devices and (5) Output devices
- Not all "memory" are created equally
 - Cache: fast (expensive) memory are placed closer to the processor
 - Main memory: less expensive memory--we can have more
- Input and output (I/O) devices have the messiest organization
 - Wide range of speed: graphics vs. keyboard
 - Wide range of requirements: speed, standard, cost ...
 - Least amount of research (so far)

Summary: Computer System Components



• All have interfaces & organizations

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Instruction Set Architecture

Instruction Set Architecture of a machine is an abstraction Interface between the hardware and the lowest-level software

•Includes anything that programmers need to know to make a binary machine program work correctly, including

✓Instructions (categories, format, ..)

 \checkmark I/O devices, # of registers, memory access schemes , ...

ISA design principles

•Simplicity favors regularity

•Smaller is faster

•Make the common case fast

ISA: What must be specified?

- Instruction Format or Encoding - how is it decoded?
- Location of operands and result
- where other than memory?
- how many explicit operands?
- how are memory operands located?
- which can or cannot be in memory?
- Data type and Size
- Operations

Instruction Fetch

Instruction

Decode

Operand

Fetch

Execute

Result

Store

Next

Instruction

- what are supported
- Successor instruction
- jumps, conditions, branches

Registers

•A storage device (in MIPS holds 32 bits, a word)

•Registers are built into the processor, in particular in the section labeled "Data Path"

•Faster than main memory

•The basic ISA classes are distinguished by

> what kinds of registers they have

 \succ what are the functions of the registers

Basic ISA Classes

Accumulator known as 1-operand machines

Use 1 register for source as well as destination operands

1-operand	Add A	$acc \leftarrow acc + mem[A]$	
	Load A	$acc \leftarrow mem[A]$	
	Store B	$mem[B] \leftarrow acc$	

Stack known as 0-operand machines

Operands are pushed and popped off an internal stack

All other operations remove their operands from the stack and replace them with the result

	Push A	push (mem[A])
0-operand	Push B	push (mem[B])
	Add	push (pop+pop)
	Pop C	$mem[A] \leftarrow pop$

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Basic ISA Classes

General Purpose	Register			
Limited number	Limited number of registers to store data for any purpose			Code sequence for C
Memory-Me	mory or Register-M	lemory		
(arithmetic in	nstructions can use	data in memory for operands))	Stack
1-operand	Add Ra, B	$Ra \leftarrow Ra + mem[B]$		
2-operand	Add A,B	$mem[A] \leftarrow mem[A] + meters$	em[B]	Push A
3-operand	Add A,B,C	$mem[A] \leftarrow mem[B] + me$	em[C]	Push B
Load/Store	Load/Store (arithmetic instructions can only use data in registers)		Add	
(register-re	egister machines)			Pop C
	Add Ra,Rb,Rc	$Ra \leftarrow Rb + Rc$		
	Load Ra,A	$Ra \leftarrow mem[A]$		
	Store Ra,B	$mem[B] \leftarrow Ra$		

Comparison of ISA classes

Code sequence for C = A + B for classes of instruction sets:

Stack	Accumulator	Register
		(load-store)
Push A	Load A	Load R1,A
Push B	Add B	Load R2,B
Add	Store C	Add R3,R1,R2
Pop C		Store C,R3

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Which ISA dominates?

General purpose registers dominate

1975-1995 all machines use general purpose registers

Advantages of registers

•registers are faster than memory

•registers are easier for a compiler to use e.g., (A*B) – (C*D) – (E*F) can do multiplies in any order vs. stack

 •registers can hold variables
> memory traffic is reduced, so program is sped up (since registers are faster than memory)
> code density improves (since register named with fewer bits than memory location

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